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		United Kingdom 8311565.001		
4.	Title of the invention	Caterpillar Traction Apparatus		
5.	Name of your agent (if you have one)	DUMMETT COPP		
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CATERPILLAR TRACTION APPARATUS

This invention relates to the field of caterpillar traction apparatuses.

5

Caterpillar traction apparatus are commonly used in the manufacturing industry to transport products along assembly lines and from one stage in the manufacturing process to the next. In particular, the cable manufacturing industry uses caterpillar traction apparatus to transport extruded plastic tubes and other cable elements between different pieces of equipment, for example between an extruder and a stranding machine.

15 According to a first aspect of the invention there is provided a caterpillar traction apparatus comprising first and second extensible traction members, the first traction member being driven by and entrained around first and second rotatable members and the second traction member
20 being driven by and entrained around third and fourth rotatable members, each of the rotatable members being addressed by drive means such that the first and third rotatable members can be driven at a first speed and the second and fourth rotatable members can be driven at a
25 second speed, the first speed not being equal to the second speed.

The difference between the first speed and the second speed may be between 1% and 10%, and in particular the
30 difference between the first speed and the second speed

may be 4%. The second speed may be less than the first speed or alternatively the second speed may be greater than the first speed. The first and second extensible traction members may be extended in a direction
5 significantly parallel to their direction of motion and/or the first and second extensible traction members may be extended in a direction significantly perpendicular to their direction of motion.

10 According to a second aspect of the invention there is provided a method of processing a linear member within a caterpillar traction apparatus according to the first aspect, wherein the processing of the linear member is effected by the difference between the first speed and the
15 second speed. The difference between the first speed and the second speed may compress linearly the linear member or alternatively the difference between the first speed and the second speed may extend linearly the linear member.

20 According to a third aspect of the invention there is provided an extensible belt for use with a caterpillar traction apparatus according to the first aspect. Preferably, the belt is capable of sustained extensions of
25 10% or greater, and the belt may comprise rubber and/or a compressible polymer.

The invention will now be described, by way of example only, with reference to the following Figures in which:

30

Figure 1 shows a schematic depiction of a known caterpillar traction mechanism;

Figure 2 shows a schematic depiction of a caterpillar traction mechanism according to the present invention; and

Figure 3 shows an alternative embodiment of schematic depiction of a caterpillar traction mechanism according to the present invention.

10 Figure 1 shows a schematic depiction of a known caterpillar traction apparatus. The caterpillar traction apparatus 10 comprises an upper half 20 and a lower half 30 that co-operate to advance a linear member 40, such as an extruded tube, pipe or cable.

15

The upper half 20 comprises a first belt 21, first and second pulleys 22, 23 and a plurality of compression rollers 24, 25, 26, 27, 28. The first belt 21 is substantially un-extended under the tensile loads experienced during normal operation of the apparatus 10. Typically such belts have a soft rubber outer layer in order to increase the grip on the linear member 40 being driven by the apparatus and comprise a substantially inextensible strength member, for example, woven aramid fibres or braided steel, in the centre of the belt, to provide the belt's capacity to resist extension. The belt may also have a tread pattern on its inner surface to increase the traction between the first belt and the first and second pulleys.

30

The first pulley 22 is a driven pulley, which is in driveable connection with a motor (not shown) whilst second pulley 23 is an idle pulley. The compression rollers 24 - 28 are free to rotate but act to urge the first belt against the linear member 40, thereby increasing the grip between the first belt and the linear member.

The lower half is of a similar construction to the upper half and comprises a second belt 31, third and fourth pulleys 32, 33 and a plurality of compression rollers 34, 35, 36, 37, 38. The second belt 31 is substantially unextended under the tensile loads experienced during normal operation of the apparatus 10 and has a similar construction and performance to the first belt (see above).

The third pulley 32 is a driven pulley, which is in driveable connection with a motor (not shown) whilst fourth pulley 33 is an idle pulley. The compression rollers 34 - 38 are free to rotate but act to urge the second belt against the linear member 40.

The traction apparatus advances the linear member by the action of the motor causing the first pulley 22 to rotate in a counter-clockwise direction and the third pulley 32 to rotate in a clockwise direction. The two sets of compression rollers work in combination to improve the grip of the first and second belts on the linear member, increasing the efficiency with which the linear member is

moved by the traction apparatus.

Figure 2 shows a caterpillar traction apparatus according to the present invention, which comprises an upper half
5 120 and a lower half 130 that co-operate to advance a linear member 40, such as an extruded tube, pipe or cable. The upper half 120 comprises a first belt 121, first and second pulleys 122, 123 and a plurality of compression rollers 124, 125, 126, 127, 128. The first belt 121 has
10 a soft rubber outer layer in order to increase the grip on the linear member 40 being driven by the apparatus and a tread pattern on the inner surface to increase the traction between the first belt and the first and second pulleys. Both the first pulley 122 and the second pulley
15 123 are driven pulleys, which have a respective driveable connection with a motor (not shown). The compression rollers 124 - 128 are free to rotate but act to urge the first belt against the linear member 40.

20 The lower half is of a similar construction to the upper half and comprises a second belt 131, third and fourth pulleys 132, 133 and a plurality of compression rollers 134, 135, 136, 137, 138. The second belt 131 has a soft rubber outer layer and a tread pattern on its inner
25 surface, in a similar manner to the first belt. The third pulley 132 and fourth pulley 133 are driven pulleys, which have a respective driveable connection with a motor (not shown). The compression rollers 134 - 138 are free to rotate but act to urge the second belt against the linear
30 member 40. Both sets of compression rollers, 124-128 &

134-138 act in a direction that is substantially normal to the linear member being passed through the apparatus

In contrast to the known arrangement described above and shown in Figure 1, both the first and second belts 121, 131 are elastic and are capable of sustaining a significant elongation, for example of 10-15%. Additionally, the second and fourth pulleys 123, 133 can be moved parallel to the axis of the linear member to stretch the first and second belts respectively.

The traction apparatus 110 according to the present invention can be used to linearly compress a linear member 40 as it passes through the apparatus. The second and fourth pulleys are moved so as to extend the first and second belts into the positions indicated by the dotted lines in Figure 2. This strains the first and second belts, giving an extension of, for example, 5%. The belts are then rotated by driving each of the pulleys. The first and second pulleys 122, 123 are both driven in a counter-clockwise direction and the third and fourth pulleys 132, 133 are driven in a clockwise direction. The second and fourth pulleys 123, 133 are driven at a lower speed than are the first and third pulleys 122, 132, for example 4% slower than the first and third pulleys. Each pulley may have a dedicated motor and drive circuitry, all of which are controlled centrally, or the apparatus may have a single motor that is connected to each pulley via respective gearings and drive circuitry.

30

This differential speed for the two sets of pulleys means that the first and second belts will be subject to different levels of strain in different regions of each belt. In the 'interior portion' of the two belts, where
5 the first belt is advanced from the first pulley to the second pulley and the second belt is advanced from the third pulley to the fourth pulley, the first and second belts are relaxed by 4% due to the speed differential, leaving the belts strained at 1%. Similarly, in the
10 'exterior portion' of the two belts, where the first belt is returned from the second pulley to the first pulley and the second belt is returned from the fourth pulley to the third pulley, the first and second belts are strained by a further 4%, giving a 9% strain in the 'exterior portion'
15 of the first and second belts.

As the linear member passes through the apparatus it is pulled into the apparatus by the first and second pulleys at a speed that is 4% greater than the speed at which the
20 third and fourth pulleys are driving the linear member out of the apparatus. Thus, the linear member is subjected to a 4% compression whilst it is being driven through the apparatus. If necessary, the force applied by the compression rollers can be increased to reduce the
25 possibility that the compressive forces induce buckling in the linear member.

By compressing the linear member the linear member can be conditioned by reducing the level of strain energy stored
30 within the member. This strain energy is incorporated

within the linear member during extrusion (or other manufacturing processes). The reduction of the stored strain energy reduces the potential for the linear member to relax. This is advantageous because it makes the subsequent storage and processing of the linear member more simple. Any such relaxation could cause an undesired change in length of the linear member, during future temperature or other environmental changes. This is of advantage when used with the tube processing equipment described in our European patent EP-B-0 765 214.

Furthermore, the apparatus of the present invention can be operated in a different manner to provide a tensile strain on the linear member, rather than a compressive strain, as it is driven through the apparatus.

To provide a tensile strain it is necessary to drive the second and fourth pulleys faster than the first and third pulleys, such that the 'interior portion' of the two belts experiences a greater strain than the 'exterior portion' of the two belts, causing the linear member to be pulled out of the apparatus by the second and fourth pulleys at a greater speed than it is driven into the apparatus by the first and third pulleys. The advantage of subjecting the linear member to a tensile strain is that polymer chains in an extruded tube can obtain a greater degree of orientation, leading to an increased tensile strength.

From the foregoing discussion it will be apparent that the capacity of the apparatus to apply compression (or

extension) to a linear member is determined by the amount of strain that the first and second belts can withstand, and the frictional grip between the belts and the driven pulleys. Known belts for caterpillar apparatus are
5 designed to operate without undergoing significant extension, as the energy that is used to extend the belts is lost from the primary purpose of the caterpillar, that is transporting an item. For example, a typical known belt for a caterpillar apparatus would have a normal
10 working strain range of 2-5% with an ultimate tensile strain of 10%. For the present invention it is envisaged that the extensible belts would have a normal working strain range of 10-20% with a much greater ultimate tensile strain value.

15
Figure 3 shows an alternative embodiment of the present invention, in which the second fourth pulleys can not be moved to extend the belts. Instead, the belts are extended by providing a plurality of rollers 300, 301, 302
20 & 303. The rollers are free to rotate and can be moved outwards (as shown in Figure 3) in order to extend the belts. The rollers are mounted on sliding blocks which comprise tensioning members such that the blocks can be secured in position. The degree of belt extension will
25 increase with the distance that the rollers are moved from their initial positions. The position of the extended belts are shown using broken lines in Figure 3. It will be understood that that the method of extending the belts described in relation to Figure 2 could be combined with
30 the method of extending the belts described in relation to

Figure 3.

It will be understood that rather than moving the second and fourth pulleys to strain the belts, the belts could be
5 provided 'too short' for the distance between the first and third pulleys and the second and fourth pulleys, such that the belts are tensioned by fitting them over their respective pairs of pulleys. However, this alternative
method is not preferred due to the increased difficulty of
10 fitting the strained belts over the pulleys.

Furthermore, it is possible to operate the apparatus according to the present invention without pre-straining the belts by moving the pulleys or by using belts that are
15 too short and this is achieved by providing the differential strain in the 'interior portion' and the 'exterior portion' solely by varying the first and second speeds, however it is believed that the tensioning of the belt will require so much energy from the driven pulleys
20 that there will be less energy available to process the linear member being driven through the apparatus and under certain conditions it may not be possible to transfer sufficient energy to the linear member to achieve the desired degree of processing.

25 It is also believed that the differential speed between the two sets of pulleys can be increased by driving the slower moving set of pulleys in the reverse direction to that described above, however this will lead to
30 significant heat generation and increased wear occurring

to the inner surface of the belts. Conventionally, caterpillar machines are arranged to provide maximum drive transfer and to minimise belt slippage, but some features, such as 'multi-vee' drive pulleys and belt profiles, may
5 be altered in order to allow significant slippage to enable one set of pulleys to be driven in reverse without causing any significant problems.

It is a known characteristic of rubber that it is
10 incompressible. Therefore, if an extensible belt comprises a significant proportion of rubber it will be necessary to extend the belt before any compression can be developed within a region of the belt. Furthermore, as
15 the compression is being developed by working against the extension previously generated within the belt, the level of compression that can be developed will be limited by the level of extension present in the belt. Clearly belts
could be made with other materials, either in place of or
in addition to rubber, such as a foamed polymer, that are
20 capable of being compressed and thus do not need to be extended before compression can be developed in a region of the belt.

CLAIMS

1. A caterpillar traction apparatus comprising first and second extensible traction members, the first traction member being driven by and entrained around first and second rotatable members and the second traction member being driven by and entrained around third and fourth rotatable members, each of the rotatable members being addressed by drive means such that the first and third rotatable members can be driven at a first speed and the second and fourth rotatable members can be driven at a second speed, the first speed not being equal to the second speed.
2. A caterpillar traction apparatus according to claim 1, wherein the difference between the first speed and the second speed is between 1% and 10%.
3. A caterpillar traction apparatus according to claim 2, wherein the difference between the first speed and the second speed is 4%.
4. A caterpillar traction apparatus according to any preceding claim, wherein the second speed is less than the first speed.
5. A caterpillar traction apparatus according to any one of claims 1 to 3, wherein the second speed is greater than the first speed.

30

6. A caterpillar traction apparatus according to any preceding claim in which the first and second extensible traction members are extended in a direction significantly parallel to their direction of motion.

5

7. A caterpillar traction apparatus according to any preceding claim in which the first and second extensible traction members are extended in a direction significantly perpendicular to their direction of motion.

10

8. A method of processing a linear member within a mechanical caterpillar apparatus according to any of claims 1 to 3, wherein the processing of the linear member is effected by the difference between the first speed and the second speed.

15

9. A method of processing a linear member according to claim 6, wherein the difference between the first speed and the second speed compresses linearly the linear member.

20

10. A method of processing a linear member according to claim 6, wherein the difference between the first speed and the second speed extends linearly the linear member.

25

11. An extensible belt for use with a mechanical caterpillar apparatus according to any of claims 1 to 7.

12. An extensible belt according to claim 11, wherein the belt is capable of sustained extensions of 10% or greater.

30

13. An extensible belt according to claim 11 or claim 12,
wherein the belt comprises rubber.

5 14. An extensible belt according to any of claims 11 to
13, wherein the belt comprises a compressible polymer.

15. A mechanical caterpillar apparatus substantially as
described herein and with reference to Figure 2 or Figure
10 3.

16. An extensible belt substantially as described herein
and with reference to Figure 2 and Figure 3.

ABSTRACT

CATERPILLAR TRACTION APPARATUS

- 5 A caterpillar traction apparatus (110), wherein two pairs of pulleys (122 & 133, 132 & 133) can be driven at different speeds, so that the linear member (40) being driven by the mechanism is subjected to either compression or extension forces.

10

Figure 2

1/2

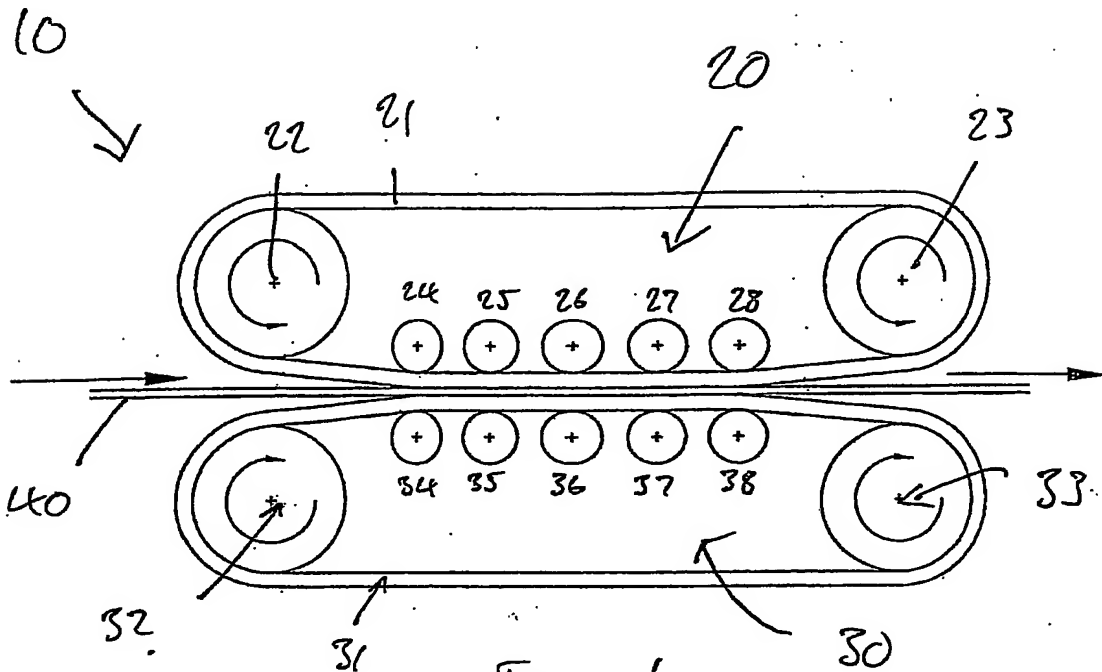


Fig. 1

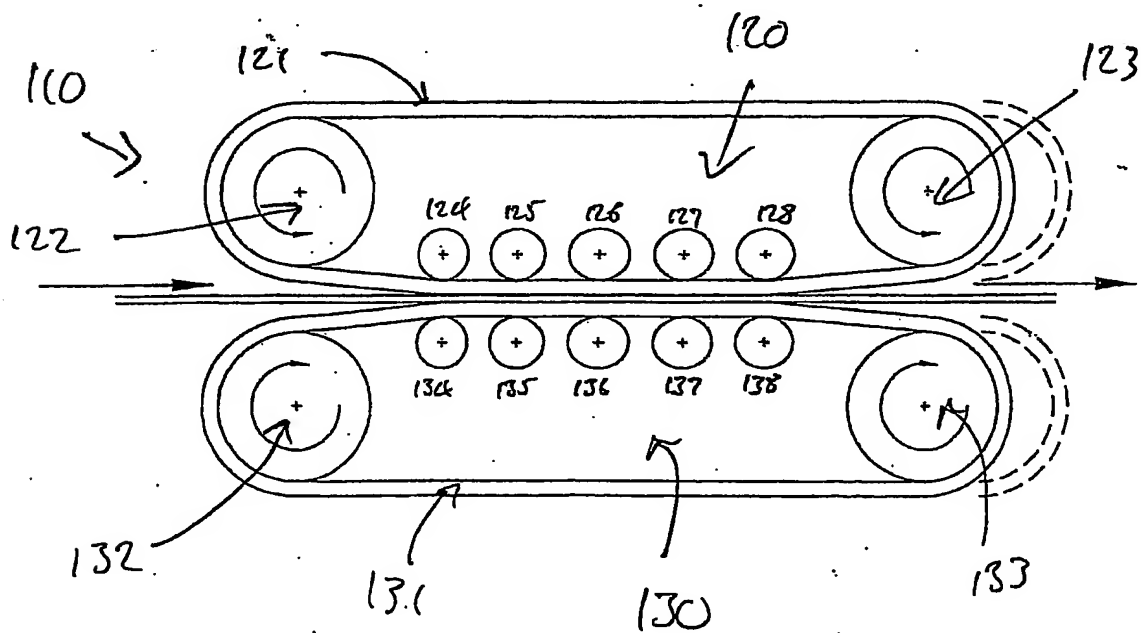


Fig. 2

2/2

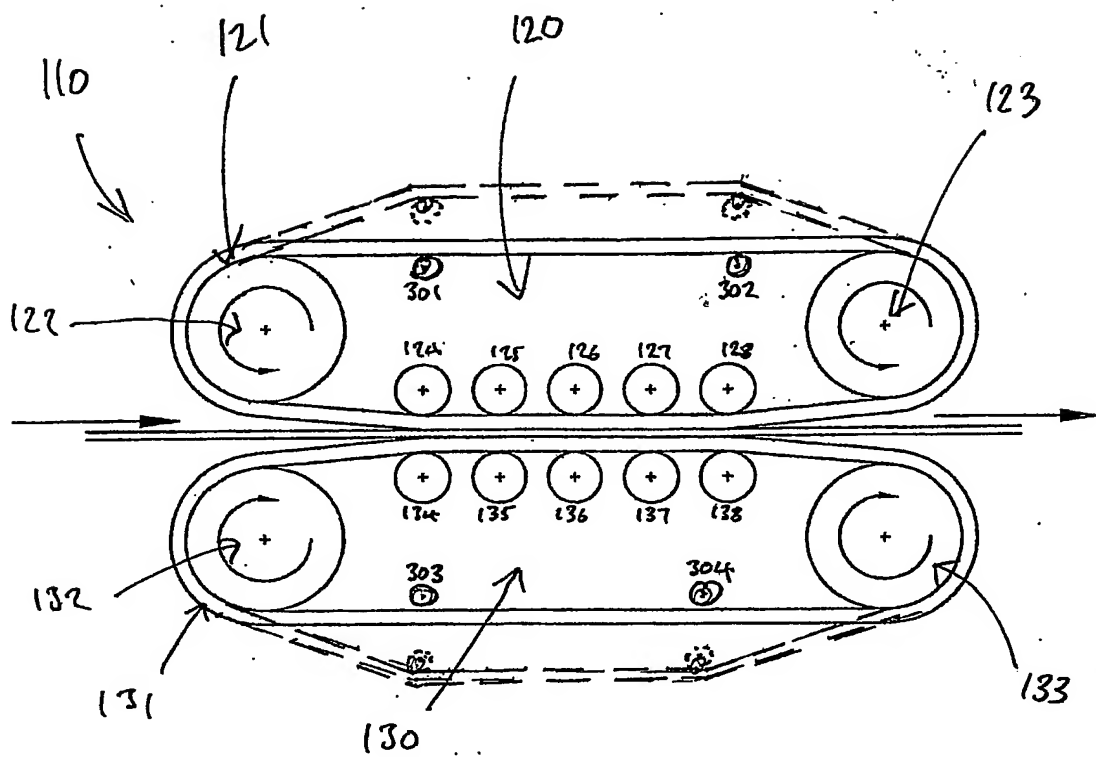


Fig. 3

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